

# A priori convergence of the Generalized Empirical Interpolation Method

Yvon Maday

UPMC Univ Paris 06, UMR 7598,  
Laboratoire Jacques-Louis Lions,  
F-75005, Paris, France.  
and Institut Universitaire de France  
and Division of Applied Mathematics,  
Brown University, Providence RI, USA.  
Email: maday@ann.jussieu.fr

Olga Mula

CEA Saclay,  
DEN/DANS/DM2S/SERMA/LLPR  
91191 Gif-Sur-Yvette CEDEX - France  
and LRC MANON,  
Laboratoire de Recherche Conventi n e  
CEA/DEN/DANS/DM2S  
and UPMC-CNRS/LJLL.  
Email: olga.mulahernandez@cea.fr

Gabriel Turinici

CEREMADE  
Universite Paris Dauphine  
Place du Marechal de Lattre de Tassigny  
75016 Paris, France  
Email: Gabriel.Turinici@dauphine.fr

**Abstract**—In an effort to extend the classical Lagrangian interpolation tools, new interpolating methods that use general interpolating functions are explored. The Generalized Empirical Interpolation Method (GEIM) belongs to this class. It generalizes the plain Empirical Interpolation Method [1] by replacing the evaluation at interpolating points by application of a class of interpolating linear functions. Since its efficiency depends critically on the choice of the interpolating functions (that are chosen by a Greedy selection procedure), the purpose of this paper is therefore to provide a priori convergence rates for the Greedy algorithm that is used to build the GEIM interpolating spaces.

## I. INTRODUCTION

The extension of the Lagrangian interpolation process is an old problem that is still currently subject to active research (see, e.g. [1] and also the activity concerning the kriging [2], [3] in the stochastic community). While this classical method approximates general functions by finite sums of well chosen, linearly independent interpolating functions (e.g. polynomial functions) and the optimal location of the interpolating points is well documented (and completely solved in one dimension), the question remains on how to approximate general functions by finite expansions involving general interpolating functions and how to optimally select the interpolation points in this case.

One step in this direction is the Empirical Interpolation Method (EIM, [4], [5], [1]) that has been developed in the broad framework where the functions  $f$  to approximate belong to a compact set  $F$  of a Banach space  $\mathcal{X}$ . The set  $F$  is supposed to be such that any  $f \in F$  is approximable by linear combinations of small size. In particular, this is the case when the Kolmogorov  $n$ -width of  $F$  in  $\mathcal{X}$  is small. Indeed, the Kolmogorov  $n$ -width of  $F$  in  $\mathcal{X}$  is defined by  $d_n(F, \mathcal{X}) := \inf_{\substack{X_n \subset \mathcal{X} \\ \dim(X_n) = n}} \sup_{x \in F} \inf_{y \in X_n} \|x - y\|_{\mathcal{X}}$  (see [6]) and measures the extent to which  $F$  can be approximated by finite dimensional spaces  $X_n \subset \mathcal{X}$  of dimension  $n$ . The Empirical Interpolation Method builds simultaneously the set

of interpolating functions and the associated interpolating points by a greedy selection procedure (see [4]).

A recent generalization of this interpolation process consists in replacing the evaluation at interpolating points by application of a class of interpolating continuous linear functions chosen in a given dictionary  $\Sigma \subset \mathcal{L}(F)$  and this gives rise to the so-called Generalized Empirical Interpolation Method (GEIM, [7]). In this newly developed method, the particular case where the space  $\mathcal{X} = L^2(\Omega)$  is considered, with  $\Omega$  being a bounded spatial domain of  $\mathbb{R}^d$  and  $F$  being a compact set of  $L^2(\Omega)$ .

In the present work, we analyze the quality of the finite dimensional subspaces  $X_n$  contained in the span of  $F$  built by the greedy selection procedure of GEIM together with the properties of the associated interpolation operator. For this purpose, the accuracy of the approximation in  $X_n$  of the elements of  $F$  will be compared to the best possible performance which is the Kolmogorov  $n$ -width  $d_n(F, L^2(\Omega))$ .

The methodology developed in this paper is in the spirit of the greedy reduced basis method. Alternative approaches exist like POD and gappy POD or even Adaptive Cross Approximation. We refer to the review paper [8] for a comparative presentation of all these sampling approaches.

The proceeding is organized as follows: after a brief recall of GEIM's Greedy algorithm (section II), we will analyze in sections III and IV some convergence decay rates of the generalized empirical interpolation error as the dimension  $n$  of  $X_n$  increases and when  $d_n(F, L^2(\Omega))$  has a polynomial or an exponential decreasing behavior.

## II. THE GENERALIZED EMPIRICAL INTERPOLATION METHOD

In the following, we assume that the dimension of the vectorial space spanned by  $F$  is of dimension  $\geq N$ .

In a similar procedure as in the Empirical Interpolation Method (EIM) [4], [5], [1], the Generalized EIM allows to define simultaneously the set of interpolating functions recursively chosen in  $F$  together with the associated linear

functions selected from a dictionary of continuous linear forms  $\Sigma \subset \mathcal{L}(F)$ , with norm 1 in  $L^2(\Omega)$ . The dictionary has the additional property that if  $\varphi \in F$  is such that  $\sigma(\varphi) = 0$  for any  $\sigma \in \Sigma$ , then  $\varphi = 0$ . The selection of the interpolating functions and linear forms is based on a greedy selection procedure as outlined in [7].

The first interpolating function is, e.g.:  $\varphi_0 = \arg \sup_{\varphi \in F} \|\varphi\|_{L^2(\Omega)}$ . The first interpolating linear form is  $\sigma_0 = \arg \sup_{\sigma \in \Sigma} |\sigma(\varphi_0)|$ . We then define the first basis function as  $q_0 = \frac{\varphi_0}{\sigma_0(\varphi_0)}$ . The second interpolating function is  $\varphi_1 = \arg \sup_{\varphi \in F} \|\varphi - \sigma_0(\varphi)q_0\|_{L^2(\Omega)}$ . The second interpolating linear form is  $\sigma_1 = \arg \sup_{\sigma \in \Sigma} |\sigma(\varphi_1 - \sigma_0(\varphi_1)q_0)|$  and the second basis function is defined as  $q_1 = \frac{\varphi_1 - \sigma_0(\varphi_1)q_0}{\sigma_1(\varphi_1 - \sigma_0(\varphi_1)q_0)}$ .

We then proceed by induction : assume that we have built the set of interpolating functions  $\{q_0, q_1, \dots, q_{N-1}\}$  and the set of associated interpolating linear forms  $\{\sigma_0, \sigma_1, \dots, \sigma_{N-1}\}$ , for  $1 \leq N \leq N_{max}$ , with  $N_{max} \leq \mathcal{N}$  being an upper bound fixed *a priori*. For  $N \leq 1$ , we first solve the interpolation problem: find  $\{\alpha_j^N(\varphi)\}_j$  such that:  $\forall i = 0, \dots, N-1$ ,  $\sigma_i(\varphi) = \sum_{j=0}^{N-1} \alpha_j^N(\varphi) \sigma_i(q_j)$ . We then compute

$\mathcal{J}_N[\varphi] = \sum_{j=0}^{N-1} \alpha_j^N(\varphi) q_j$  and evaluate  $\varepsilon_N(\varphi) = \|\varphi - \mathcal{J}_N[\varphi]\|_{L^2(\Omega)}$ ,  $\forall \varphi \in F$ . We define  $\varphi_N = \arg \sup_{\varphi \in F} \varepsilon_N(\varphi)$  and  $\sigma_N = \arg \sup_{\sigma \in \Sigma} |\sigma(\varphi_N - \mathcal{J}_N[\varphi_N])|$ . The next basis function is then  $q_N = \frac{\varphi_N - \mathcal{J}_N[\varphi_N]}{\sigma_N(\varphi_N - \mathcal{J}_N[\varphi_N])}$

We finally set  $X_{N+1} \equiv \text{span}\{q_j, j \in [0, N]\} = \text{span}\{\varphi_j, j \in [0, N]\}$ . It has been proven in [7]:

**Lemma 1:** For any  $N \leq \mathcal{N}$ , the set  $\{q_j, j \in [0, N-1]\}$  is linearly independent and  $X_N$  is of dimension  $N$ . The generalized empirical interpolation procedure is well-posed in  $L^2(\Omega)$  and  $\forall \varphi \in F$ , the interpolation error satisfies:

$$\|\varphi - \mathcal{J}_N[\varphi]\|_{L^2(\Omega)} \leq (1 + \Lambda_N) \inf_{\psi_N \in X_N} \|\varphi - \psi_N\|_{L^2(\Omega)}$$

where  $\Lambda_N$  is the Lebesgue constant in the  $L^2$  norm:  $\Lambda_N := \sup_{\varphi \in F} \frac{\|\mathcal{J}_N[\varphi]\|_{L^2(\Omega)}}{\|\varphi\|_{L^2(\Omega)}}$ .

**Remark 1:** In a similar way as in the classical Lagrangian interpolation, the Lebesgue constant  $\Lambda_N$  defined in our generalized interpolation procedure depends both on set  $F$  and on the choice of the dictionary of continuous linear forms  $\Sigma$  but no detailed analysis of the behavior of  $\Lambda_N$  as a function of  $F$  or  $\Sigma$  has been carried out so far.

**Remark 2:** In practice the selection of the interpolation functions in  $F$  and the interpolating elements in the dictionary can be done by discretizing both  $F$  and  $\Sigma$  as is the case for standard greedy approximations like in [5], [6]; an alternative approach is [9] where the selection is done through a continuous algorithm based on an iterative sequence of optimization problems (solved by Newton methods) that seek to maximize the error between the RB approximation and the underlying true solution. The interpolants can be efficiently computed recursively as outlined in [10].

### III. PRELIMINARY NOTATIONS AND BASIC PROPERTIES

In what follows, we denote by  $(\varphi_n^*)_{n \geq 0}$  the orthonormal system obtained from  $(\varphi_n)_{n \geq 0}$  by Gram-Schmidt orthogonalization.

For any  $n \geq 1$ , we define the orthogonal projector  $P_n$  from  $\mathcal{X}$  onto  $X_n$  which is given by  $P_n(f) = \sum_{j=0}^{n-1} \langle f, \varphi_j^* \rangle \varphi_j^*$ ,  $\forall f \in F$ , where  $\langle \cdot, \cdot \rangle$  is the  $L^2(\Omega)$  scalar product. In particular:  $\varphi_n = P_{n+1}(\varphi_n) = \sum_{j=0}^n a_{n,j} \varphi_j^*$ , with  $a_{n,j} := \langle \varphi_n, \varphi_j^* \rangle$ ,  $0 \leq j \leq n$ .

Finally, let us denote  $\tau_0(F)_{L^2(\Omega)} := d_0(F, L^2(\Omega))$  and, for any  $n \geq 1$ :  $\tau_n := \tau_n(F)_{L^2(\Omega)} := \max_{f \in F} \|f - P_n(f)\|_{L^2(\Omega)}$  and by  $\gamma_n$  the constant  $\gamma_n = 1/(1 + \Lambda_n)$ .

We begin by proving the two following lemmas:

**Lemma 2:** For any  $n \geq 1$ ,  $\|\varphi_n - P_n(\varphi_n)\|_{L^2(\Omega)} \geq \gamma_n \tau_n(F)$ .

*Proof:* From lemma 1 applied to  $\varphi = \varphi_n$  we have  $\|\varphi_n - P_n(\varphi_n)\|_{L^2(\Omega)} \geq \gamma_n \|\varphi_n - \mathcal{J}_n(\varphi_n)\|_{L^2(\Omega)}$ . But  $\|\varphi_n - \mathcal{J}_n(\varphi_n)\|_{L^2(\Omega)} \geq \|\varphi - \mathcal{J}_n(\varphi)\|_{L^2(\Omega)}$  for any  $\varphi \in F$  according to the definition of  $\varphi_n$ . Thus  $\|\varphi_n - P_n(\varphi_n)\|_{L^2(\Omega)} \geq \gamma_n \|\varphi - \mathcal{J}_n(\varphi)\|_{L^2(\Omega)} \geq \gamma_n \|\varphi - P_n(\varphi)\|_{L^2(\Omega)}$ . ■

**Lemma 3:** Let  $A$  be the lower triangular matrix defined by  $A := (a_{i,j})_{i,j=0}^{\infty}$  ( $a_{i,j} := 0$ ,  $j > i$ ).  $A$  has two important properties:

- P1:  $\gamma_n \tau_n \leq |a_{n,n}| \leq \tau_n$ .
- P2: For every  $m \geq n$ ,  $\sum_{j=n}^m a_{m,j}^2 \leq \tau_n^2$ .

*Proof:*

- P1:  $\forall f \in F$ :  $P_n(f) = \sum_{j=0}^{n-1} \langle f, \varphi_j^* \rangle \varphi_j^*$ . In particular:  $\varphi_n - P_n(\varphi_n) = a_{n,n} \varphi_n^* \Rightarrow \|\varphi_n - P_n(\varphi_n)\|_{L^2(\Omega)}^2 = a_{n,n}^2$ . The upper bound is thus obvious and Lemma 2 gives the lower bound.
- P2: For every  $m \geq n$ :  $\sum_{j=n}^m |a_{m,j}|^2 = \|\varphi_m - P_n(\varphi_m)\|_{L^2(\Omega)}^2 \leq \max_{f \in F} \|f - P_n(f)\|^2 = \tau_n^2$ . ■

### IV. A PRIORI CONVERGENCE RATES OF THE GEIM GREEDY METHOD

In order to get convergence decay rates in the generalized interpolation error of our method, we first note that lemma 2 shows that the GEIM's Greedy algorithm is what is called in [11] a "weak Greedy algorithm" of parameter  $\gamma_n = 1/(1 + \Lambda_n)$  that depends on the dimension of  $X_n$ .

Thanks to this observation, we shall derive convergence decay rates in the sequence  $(\tau_n)_{n \geq 0}$ . This task consists in extending the proofs of [11] where the constant case  $\gamma_n = \gamma$  was addressed and where the following two results were proven in Corollary 3.3:

- i) If  $d_n(F) \leq C_0 n^{-\alpha}$  for  $n \geq 1$ , then  $\tau_n \leq C_0 2^{5\alpha+1} \gamma^{-2} n^{-\alpha}$  for  $n \geq 1$ .
- ii) If  $d_n(F) \leq C_0 e^{-c_0 n^\alpha}$  for  $n \geq 1$ , then  $\tau_n \leq \sqrt{2} C_0 \gamma^{-1} e^{-c_1 n^\alpha}$  for  $n \geq 1$ , where  $c_1 := 2^{-1-2\alpha} c_0$ .

In order to extend *i)* and *ii)* to the more general case where  $\gamma$  depends on the dimension  $n$ , the following preliminary theorem is required:

**Theorem 4:** For any  $N \geq 0$ , consider the weak Greedy algorithm with constant  $\gamma_N$  in  $L^2(\Omega)$  associated with the compact set  $F$ . We have the following inequalities between  $\tau_N$  and  $d_N := d_N(F, L^2(\Omega))$ : for any  $K \geq 1$ ,  $1 \leq m < K$

$$\prod_{i=1}^K \tau_{N+i}^2 \leq \frac{1}{\prod_{i=1}^K \gamma_{N+i}^2} \left(\frac{K}{m}\right)^m \left(\frac{K}{K-m}\right)^{K-m} \tau_{N+1}^{2m} d_m^{2(K-m)}.$$

*Proof:* This result is an extension of Theorem 3.2 of [11] to the case where the parameter of the weak Greedy algorithm ( $\gamma_N$ ) depends on the dimension of the reduced space  $X_N$ . Its proof is a slight modification to the one provided in [11] using  $\gamma_N$  and the properties P1 and P2 stated in Lemma 3. ■

Using theorem 4, convergence rates in the sequence  $(\tau_n)_{n \geq 0}$  when  $(d_n)_{n \geq 0}$  has a polynomial or an exponential decay can be inferred and lead to lemmas 5 and 6:

**Lemma 5 (Polynomial decay of  $(d_n)_{n \geq 0}$ ):** For any  $n \geq 1$ , let  $n = 4\ell + k$  (where  $\ell \in \{0, 1, \dots\}$  and  $k \in \{0, 1, 2, 3\}$ ). Assume that there exists a constant  $C_0 > 0$  such that  $\forall n \geq 1$ ,  $d_n(F, L^2(\Omega)) \leq C_0 n^{-\alpha}$ , then  $\tau_n \leq C_0 \beta_n n^{-\alpha}$ , where  $\beta_1 = 2$  and for  $n \geq 2$ :  $\beta_n = \beta_{4\ell+k} := \sqrt{2\beta_{\ell_1}} \frac{1}{\prod_{i=1}^{\ell_2} \gamma_{\ell_1 - \lceil \frac{k}{4} \rceil + i}^{\frac{1}{2}}}$  (where  $\ell_1 = 2\ell + \lfloor \frac{2k}{3} \rfloor$ ,  $\ell_2 = 2(\ell + \lceil \frac{k}{4} \rceil)$ ).

*Proof:* The proof is done by recurrence over  $n$ . We initialize the reasoning by proving that  $\tau_1 \leq 2C_0$  and then prove the general statement for  $n \geq 2$ .

Case  $n = 1$ : We recall that  $\varphi_0 = \arg \sup_{\varphi \in F} \|\varphi\|_{L^2(\Omega)}$  and that  $P_1$  is the projector operator onto  $\text{span}\{\varphi_0\}$ . We set:  $f_1 = \arg \tau_1 = \arg \max_{f \in F} \|f - P_1(f)\|_{L^2(\Omega)}$  and let  $\mu \in F$  span the one dimensional subspace of  $F$  for which  $d_1 \geq \|f - P_\mu(f)\|_{L^2(\Omega)}$  for any  $f \in F$  ( $P_\mu$  being the projector operator onto  $\text{span}\{\mu\}$ ). We have:  $\tau_1 = \|f_1 - P_1(f_1)\|_{L^2(\Omega)} = \|f_1 - P_\mu(f_1) + P_\mu(f_1) - P_1(f_1)\|_{L^2(\Omega)} = \|f_1 - P_\mu(f_1) - P_1(f_1 - P_\mu(f_1)) + P_\mu(f_1) - P_1 P_\mu(f_1)\|_{L^2(\Omega)} \leq d_1 + \|P_\mu(f_1) - P_1 P_\mu(f_1)\|_{L^2(\Omega)}$ .

$$\begin{aligned} \text{We have: } \|P_\mu(f_1) - P_1 P_\mu(f_1)\|_{L^2(\Omega)} &= \frac{\langle f_1, \mu \rangle \mu}{\|\mu\|_{L^2(\Omega)}^2} - \frac{\langle \langle f_1, \mu \rangle \mu, \varphi_0 \rangle \varphi_0}{\|\mu\|_{L^2(\Omega)}^2 \|\varphi_0\|_{L^2(\Omega)}^2} \\ &= \frac{|\langle f_1, \mu \rangle|}{\|\mu\|_{L^2(\Omega)}} \frac{\mu}{\|\mu\|_{L^2(\Omega)}} - \frac{\langle \varphi_0, \mu \rangle \varphi_0}{\|\mu\|_{L^2(\Omega)} \|\varphi_0\|_{L^2(\Omega)}} \end{aligned}$$

Since for any  $x, y \in F$  with norm 1 we have  $\|x - \langle x, y \rangle y\|_{L^2(\Omega)} = \|y - \langle x, y \rangle x\|_{L^2(\Omega)}$ , we deduce that:  $\|P_\mu(f_1) - P_1 P_\mu(f_1)\|_{L^2(\Omega)} = \frac{|\langle f_1, \mu \rangle|}{\|\mu\|_{L^2(\Omega)}} \frac{\varphi_0}{\|\varphi_0\|_{L^2(\Omega)}} - \frac{\langle \varphi_0, \mu \rangle \mu}{\|\mu\|_{L^2(\Omega)} \|\varphi_0\|_{L^2(\Omega)}} \|L^2(\Omega)$ .

$$\begin{aligned} \text{Hence: } \tau_1 &\leq d_1 + \frac{|\langle f_1, \mu \rangle|}{\|\mu\|_{L^2(\Omega)} \|\varphi_0\|_{L^2(\Omega)}} \varphi_0 - \frac{\langle \varphi_0, \mu \rangle \mu}{\|\mu\|_{L^2(\Omega)} \|\varphi_0\|_{L^2(\Omega)}} \\ &\leq d_1 \left( 1 + \frac{|\langle f_1, \mu \rangle|}{\|\mu\|_{L^2(\Omega)} \|\varphi_0\|_{L^2(\Omega)}} \right) \leq 2d_1. \end{aligned}$$

**Remark 3:** In the case where  $\|\varphi_0\|_{L^2(\Omega)} \geq \gamma_0 \|f\|_{L^2(\Omega)}$  for any  $f \in F$  ( $0 < \gamma_0 \leq 1$ ), we would have obtained  $\tau_1 \leq d_1 \left(1 + \frac{1}{\gamma_0}\right)$ .

Case  $n \geq 2$ : Let  $n = N + K$  for any  $N \geq 0$ ,  $K \geq 2$ . If  $i \leq K$ , we have  $\tau_n = \tau_{N+K} \leq \tau_{N+i}$  from the monotonicity of  $(\tau_n)_{n \geq 0}$ . By combining this inequality with theorem 4, if  $1 \leq m < K$ , we derive

$$\text{that } \tau_n \leq \frac{1}{\prod_{i=1}^K \gamma_{N+i}^{\frac{1}{K}}} \sqrt{\left(\frac{K}{m}\right)^{\frac{m}{K}} \left(\frac{K}{K-m}\right)^{1-\frac{m}{K}}} \tau_{N+1}^{\frac{m}{K}} d_m^{1-\frac{m}{K}} \leq \frac{1}{\prod_{i=1}^K \gamma_{N+i}^{\frac{1}{K}}} \sqrt{2} \tau_{N+1}^{\frac{m}{K}} d_m^{1-\frac{m}{K}},$$

since  $x^{-x}(1-x)^{x-1} \leq 2$  for any  $x$ ,  $0 < x < 1$ . We now use that  $d_m \leq C_0 m^{-\alpha}$  and the recurrence hypothesis in  $N+1 < n$ :  $\tau_{N+1} \leq C_0 \beta_{N+1} (N+1)^{-\alpha}$  which yields:  $\tau_{N+K} \leq C_0 \sqrt{2} \frac{1}{\prod_{i=1}^K \gamma_{N+i}^{\frac{1}{K}}} \beta_{N+1}^{\frac{m}{K}} \xi(n)^\alpha (N+K)^{-\alpha}$  where

$$\xi(n) = \frac{n}{m} \left(\frac{m}{N+1}\right)^{\frac{m}{K}}.$$

Any  $n \geq 2$  can be written as  $n = 4\ell + k$  with  $\ell \in \{0, 1, \dots\}$  and  $k \in \{0, 1, 2, 3\}$ . If  $k = 1, 2$  or  $3$ , it can easily be proven that  $\xi(n) \leq 2\sqrt{2}$  by setting  $N = 2\ell - 1$ ,  $K = 2\ell + 2$ ,  $m = \ell + 1$  if  $k = 1$  and  $\ell \geq 1$ ,  $N = 2\ell$ ,  $K = 2\ell + 2$ ,  $m = \ell + 1$  if  $k = 2$  and  $\ell \geq 0$  and  $N = 2\ell + 1$ ,  $K = 2\ell + 2$ ,  $m = \ell + 1$  if  $k = 3$  and  $\ell \geq 0$ . These choices of  $N$ ,  $K$  and  $m$  combined with the upper bound of  $\xi$  yield the result  $\tau_n \leq C_0 \beta_n n^{-\alpha}$  in the case  $k = 1, 2$  or  $3$ .

In the case  $n = 4\ell$  ( $\ell \geq 1$ ), using the fact that  $\tau_{N+1} \leq \tau_N$ , we can derive that  $\tau_n \leq \frac{1}{\prod_{i=1}^K \gamma_{N+i}^{\frac{1}{K}}} \sqrt{2} \tau_N^{\frac{m}{K}} d_m^{1-\frac{m}{K}}$ . If we choose

$$N = K = 2\ell \text{ and } m = \ell, \text{ the previous inequality directly yields } \tau_{4\ell} \leq C_0 \sqrt{2\beta_{2\ell}} \frac{1}{\prod_{i=1}^{2\ell} \gamma_{2\ell+i}^{\frac{1}{2}}} (2\sqrt{2})^\alpha (4\ell)^{-\alpha}.$$

**Lemma 6 (Exponential decay in  $(d_n)_{n \geq 0}$ ):** Assume that there exists a constant  $C_0 > 0$  such that  $\forall n \geq 1$ ,  $d_n(F, L^2(\Omega)) \leq C_0 e^{-c_1 n^\alpha}$ , then  $\tau_n \leq C_0 \beta_n e^{-c_2 n^\alpha}$ , where  $\beta_n := \frac{1}{\prod_{i=1}^{\lceil \frac{n}{2} \rceil} \gamma_{\lfloor \frac{n}{2} \rfloor + i}^{\frac{1}{2}}}$  for  $n \geq 2$ ,  $\beta_1 = 2$  and  $c_2 := 2^{-1-3\alpha} c_1$ .

*Proof:* The proof is done by recurrence over  $n$ . The case  $n = 1$  is addressed by following the same lines as in lemma 5.

In the case  $n = 2$ , we have:  $\tau_2 \leq \tau_1 \leq 2C_0$ . For  $n \geq 3$ , we start from  $\tau_{N+K} \leq \frac{1}{\prod_{i=1}^K \gamma_{N+i}^{\frac{1}{K}}} \sqrt{2} \tau_{N+1}^{\frac{m}{K}} d_m^{1-\frac{m}{K}}$

and treat the cases  $n = N + K = 2\ell$  and  $n = N + K = 2\ell + 1$  separately ( $\ell \geq 1$ ).

If  $n = N + K = 2\ell$ , we choose  $N = K = \ell$  and  $m = \lfloor \frac{K}{2} \rfloor$ .

The inequality yields  $\tau_{2\ell} \leq \frac{1}{\prod_{i=1}^{\ell} \gamma_{\ell+i}^{\frac{1}{2}}} \sqrt{2\tau_{\ell} e^{-c_2(2\ell)^\alpha}}$ .

In a similar procedure, the desired result can be inferred for  $n = N + K = 2\ell + 1$  if we choose  $N = \ell$ ,  $K = \ell + 1$  and  $m = \lfloor \frac{K}{2} \rfloor$ . ■

**Remark 4:** 1) In the case where  $\gamma_n$  is constant  $\gamma_n = \gamma$ , lemmas 5 and 6 yield results that are similar to the ones obtained in [11] (see results *i*) and *ii*) above).

2) In the case where  $(\gamma_n)_{n \geq 1}$  is a monotonically decreasing sequence, the following bounds can be derived for  $\tau_n$ :

- If  $d_n(F, L^2(\Omega)) \leq C_0 n^{-\alpha}$  for any  $n \geq 1$ , then  $\tau_n \leq C_0 \beta n^{-\alpha}$  for  $n \geq 1$ , with  $\beta := 2^{3\alpha+1} (\min_{1 \leq j \leq n} \gamma_j)^{-2} = 2^{3\alpha+1} \gamma_n^{-2}$ .
- If  $d_n(F, L^2(\Omega)) \leq C_0 e^{-c_1 n^\alpha}$  for any  $n \in \{1, 2, \dots\}$ , then  $\tau_n \leq C_0 \beta e^{-c_2 n^\alpha}$  for  $n \geq 1$ , with  $\beta := 2 (\min_{1 \leq j \leq n} \gamma_j)^{-2} = 2 \gamma_n^{-2}$ .

Lemmas 5 and 6 are the keys to derive the decay rates of the interpolation error of the GEIM Greedy algorithm. This is the purpose of the following theorem:

**Theorem 7:** 1) Assume that  $d_n(F, L^2(\Omega)) \leq C_0 n^{-\alpha}$  for any  $n \geq 1$ , then the interpolation error of the GEIM Greedy selection process satisfies for any  $\varphi \in F$  the inequality  $\|\varphi - \mathcal{J}_n[\varphi]\|_{L^2(\Omega)} \leq C_0(1 + \Lambda_n)\beta_n n^{-\alpha}$ , where the parameter  $\beta_n$  is defined as in lemma 5.

2) Assume that  $d_n(F, L^2(\Omega)) \leq C_0 e^{-c_1 n^\alpha}$  for any  $n \geq 1$ , then the interpolation error of the GEIM Greedy selection process satisfies for any  $\varphi \in F$  the inequality  $\|\varphi - \mathcal{J}_n[\varphi]\|_{L^2(\Omega)} \leq C_0(1 + \Lambda_n)\beta_n e^{-c_2 n^\alpha}$ , where  $\beta_n$  and  $c_2$  are defined as in lemma 6.

*Proof:* It can be inferred from lemma 1 that,  $\forall \varphi \in F$ ,  $\|\varphi - \mathcal{J}_n[\varphi]\|_{L^2(\Omega)} \leq (1 + \Lambda_n)\|\varphi - P_n(\varphi)\|_{L^2(\Omega)} \leq (1 + \Lambda_n)\tau_n$  according to the definition of  $\tau_n$ . We conclude the proof by bounding  $\tau_n$  thanks to lemmas 5 and 6. ■

**Remark 5:** If  $(\Lambda_n)_{n \geq 1}$  is a monotonically increasing sequence, then the sequence  $(\gamma_n)_{n \geq 1}$  in the GEIM procedure is monotonically decreasing. Using remark 4, the following decay rates in the generalized interpolation error can be derived:

- For any  $\varphi \in F$ , if  $d_n(F, L^2(\Omega)) \leq C_0 n^{-\alpha}$  for any  $n \geq 1$ , then the interpolation error of the GEIM Greedy selection process can be bounded as  $\|\varphi - \mathcal{J}_n[\varphi]\|_{L^2(\Omega)} \leq C_0 2^{3\alpha+1} (1 + \Lambda_n)^3 n^{-\alpha}$ .
- For any  $\varphi \in F$ , if  $d_n(F, L^2(\Omega)) \leq C_0 e^{-c_1 n^\alpha}$  for any  $n \geq 1$ , then the interpolation error of the GEIM Greedy selection process can be bounded as  $\|\varphi - \mathcal{J}_n[\varphi]\|_{L^2(\Omega)} \leq C_0 2(1 + \Lambda_n)^3 e^{-c_2 n^\alpha}$ .

**Remark 6:** The evolution of the Lebesgue constant  $\Lambda_N$  as a function of  $N$  is a subject of great interest. From the theoretical point of view, crude estimates exist and provide an exponential upper bound that is far from being what we get in the applications. As is shown in ([4], [5], [1]), the growth is lower than linear in  $N$  in the EIM situations. Our first numerical experiments with the GEIM reveal cases where it is uniformly bounded when evaluated in the  $\mathcal{L}(L^2)$  norm

(see [7], [10] for an illustration of this topic as well as for an application of the method to data assimilation coupled with simulation). We do not pretend that this is universal, but it only shows that the theoretical exponentially increasing upper bound is far from being optimal in a class of sets  $F$  that have a small Kolmogorov  $n$ -width.

## V. CONCLUSION

In this work, it has been proven that the approximation properties of the generalized interpolating spaces  $X_n$  lead to an error that has the same qualitative decay as the best possible choice and that is distant by a (multiplicative) factor  $(1 + \Lambda_n)\beta_n$  from it. This has been proven in the case of a polynomial or exponential convergence in the  $n$ -width and is a first step towards the explanation of efficiency of this method in practice (as outlined in [7]).

## ACKNOWLEDGEMENTS

This work was supported in part by the joint research program MANON between CEA-Saclay and University Pierre et Marie Curie-Paris 6 and also by the research grant ApProCEM - FP7-PEOPLE - PIEF-GA-2010-276487.

## REFERENCES

- [1] Y. Maday, N. Nguyen, A. Patera, and G. Pau, "A general multipurpose interpolation procedure: the magic points," *Commun. Pure Appl. Anal.*, vol. 8(1), pp. 383–404, 2009.
- [2] J. P. Kleijnen and W. C. van Beers, "Robustness of kriging when interpolating in random simulation with heterogeneous variances: Some experiments," *European Journal of Operational Research*, vol. 165, no. 3, pp. 826 – 834, 2005.
- [3] H. Liu and S. Maghsoodloo, "Simulation optimization based on taylor kriging and evolutionary algorithm," *Applied Soft Computing*, vol. 11, no. 4, pp. 3451 – 3462, 2011.
- [4] M. Barrault, Y. Maday, N. Y. Nguyen, and A. Patera, "An empirical interpolation method: Application to efficient reduced-basis discretization of partial differential equations." *C. R. Acad. Sci. Paris, Série I*, vol. 339, pp. 667–672, 2004.
- [5] M. Grepl, Y. Maday, N. Nguyen, and A. Patera, "Efficient reduced-basis treatment of nonaffine and nonlinear partial differential equations." *M2AN (Math. Model. Numer. Anal.)*, vol. 41(3), pp. 575–605, 2007.
- [6] A. Kolmogoroff, "Über die beste Annäherung von Funktionen einer gegebenen Funktionenklasse," *Annals of Mathematics*, vol. 37, pp. 107–110, 1936.
- [7] Y. Maday and O. Mula, "A generalized empirical interpolation method: application of reduced basis techniques to data assimilation," *Analysis and Numerics of Partial Differential Equations*, vol. XIII, pp. 221–236, 2013.
- [8] M. Bebendorf, Y. Maday, and B. Stamm, "Comparison of some reduced representation approximations," in *Reduced Order Methods for modeling and computational reduction, Proceedings of the CECAM Workshop: Reduced Basis, POD and Reduced Order Methods for model and computational reduction: towards real-time computing and visualization?*, 2013.
- [9] T. Bui-Thanh, K. Willcox, and O. Ghattas, "Model reduction for large-scale systems with high-dimensional parametric input space," *SIAM Journal on Scientific Computing*, vol. 30, no. 6, pp. 3270–3288, 2008.
- [10] O. Mula, "in progress," Ph.D. dissertation, Univ. Paris VI, 2014.
- [11] R. DeVore, G. Petrova, and P. Wojtaszczyk, "Greedy algorithms for reduced bases in banach spaces," *Constructive Approximation*, pp. 1–12, 2012.